

Specifying and Verifying Future Conditions

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The existing solution

<pre>void *malloc (size_t size); // pre: size>0 ∧ _[★] // post: (ret=null ∧ ε) ∨ (ret≠null ∧ malloc(ret)) // future: ret≠null → \mathcal{F} (free(ret))</pre>	$\frac{f(\bar{x}) [\Phi_{pre}, \Phi_{post}, \Phi_{future}] \in \mathcal{E} \quad [\text{FV-Call}] \quad \Phi <: \Phi_{pre} \quad \{\Phi \circ \Phi_{post}\} e \{\Phi_e\} \quad \Phi_e <: \Phi_{future}}{\{\Phi\} f(\bar{x}); e \{\Phi_{post} \circ \Phi_e\}}$
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Three main limitations:

- ❑ Inefficient ($O(n^2)$) entailment checking
- ❑ Handle loops via unrolling
- ❑ Bug-finding (no incorrectly flagged safe code) over soundness (no missed violations)

Inefficient ($O(n^2)$) entailment checking

A use-after-free bug recorded from CWE-416

```
1 int main(int argc, char **argv) {  
2     char *buf1, *buf2, *buf3;  
3     buf1 = malloc(1);  
4     buf2 = malloc(1);  
5     free(buf2);  
6     buf3 = malloc(1);  
7     strncpy(buf2, argv[1], 1);    Use-after-free!  
8     free(buf1); free(buf3); }
```


Inefficient ($O(n^2)$) entailment checking

```
void *malloc (size_t size);  
// pre: size > 0 ∧  $\_*$   
// post: (ret = null ∧  $\epsilon$ ) ∨ (ret ≠ null ∧ malloc(ret))  
// future: ret ≠ null →  $\mathcal{F}$  (free(ret))
```

```
void free (void *ptr);  
// post: true ∧ free(ptr)  
// future: true ∧  $\mathcal{G}$  (!_(ptr))
```

```
char *strncpy(char *dest, const char *source, size_t num);  
// post: true ∧ strncpy(dest)
```

$f(\bar{x}) [\Phi_{pre}, \Phi_{post}, \Phi_{future}] \in \mathcal{E}$ [FV-Call]

$$\frac{\Phi <: \Phi_{pre} \quad \{\Phi \circ \Phi_{post}\} e \{\Phi_e\} \quad \Phi_e <: \Phi_{future}}{\{\Phi\} f(\bar{x}); e \{\Phi_{post} \circ \Phi_e\}}$$

```
1 int main(int argc, char **argv) {  
2     char *buf1, *buf2, *buf3;  
3     buf1 = malloc(1);  
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5     free(buf2);  
6     buf3 = malloc(1);  
7     strncpy(buf2, argv[1], 1);    Use-after-free!  
8     free(buf1); free(buf3); }
```


Inefficient ($O(n^2)$) entailment checking

```
void *malloc (size_t size);
// pre: size>0  $\wedge$  _*
// post: (ret=null  $\wedge$   $\epsilon$ )  $\vee$  (ret!=null  $\wedge$  malloc(ret))
// future: ret!=null  $\rightarrow$   $\mathcal{F}$  (free(ret))
```

```
void free (void *ptr);
// post: true  $\wedge$  free(ptr)
// future: true  $\wedge$   $\mathcal{G}$  (!_ (ptr))
```

```
char *strncpy(char *dest, const char *source, size_t num);
// post: true  $\wedge$  strncpy(dest)
```

$f(\bar{x}) [\Phi_{pre}, \Phi_{post}, \Phi_{future}] \in \mathcal{E}$ [FV-Call]

$$\frac{\Phi <: \Phi_{pre} \quad \{\Phi \circ \Phi_{post}\} e \{\Phi_e\} \quad \Phi_e <: \Phi_{future}}{\{\Phi\} f(\bar{x}); e \{\Phi_{post} \circ \Phi_e\}}$$

```
1 int main(int argc, char **argv) {
2   char *buf1, *buf2, *buf3;
3   buf1 = malloc(1);  $\leftarrow$  malloc(buf2).free(buf2).malloc(buf3).strncpy(buf2).free(buf1).free(buf3)  $\sqsubseteq$  F(free(buf1))
4   buf2 = malloc(1);  $\leftarrow$  free(buf2).malloc(buf3).strncpy(buf2).free(buf1).free(buf3)  $\sqsubseteq$  F(free(buf2))
5   free(buf2);  $\leftarrow$  malloc(buf3).strncpy(buf2).free(buf1).free(buf3)  $\not\sqsubseteq$  G(!_ (buf2))
6   buf3 = malloc(1);  $\leftarrow$  strncpy(buf2).free(buf1).free(buf3)  $\sqsubseteq$  F(free(buf3))
7   strncpy(buf2, argv[1], 1); Use-after-free!
8   free(buf1); free(buf3); }  $\leftarrow$  free(buf3)  $\sqsubseteq$  G(!_ (buf1))
                                     empty  $\sqsubseteq$  G(!_ (buf3))
```


A new solution for reasoning FCs

2. `char *buf1, *buf2, *buf3;`

3. `buf1 = malloc(1);`

4. `buf2 = malloc(1);`

5. `free(buf2);`

6. `buf3 = malloc(1);`

7. `strncpy(buf2,argv[1],1);`

A new solution for reasoning FCs

```
2. char *buf1, *buf2, *buf3;
{ (∃buf1, buf2, buf3. true ; ε ; _*) }
3. buf1 = malloc(1);
{ (∃buf1, buf2, buf3. buf1 ≠ null ; malloc(buf1) ; ℱ(free(buf1))) }
4. buf2 = malloc(1);
{ (∃buf1, buf2, buf3. buf1 ≠ null ∧ buf2 ≠ null ; malloc(buf1) · malloc(buf2) ;
  ℱ(free(buf1)) ∧ ℱ(free(buf2))) }
5. free(buf2);
{ (∃buf1, buf2, buf3. buf1 ≠ null ∧ buf2 ≠ null ; malloc(buf1) · malloc(buf2) · free(buf2) ;
  ℱ(free(buf1)) ∧ _* ∧ ℱ(!_ (buf2))) }
6. buf3 = malloc(1);
{ (∃buf1, buf2, buf3. buf1 ≠ null ∧ buf2 ≠ null ∧ buf3 ≠ null ; malloc(buf1) · malloc(buf2)
  · free(buf2) · malloc(buf3) ; ℱ(free(buf1)) ∧ ℱ(!_ (buf2)) ∧ ℱ(free(buf3))) }
7. strncpy(buf2, argv[1], 1);
{ (∃buf1, buf2, buf3. buf1 ≠ null ∧ buf2 ≠ null ∧ buf3 ≠ null ; malloc(buf1) · malloc(buf2)
  · free(buf2) · malloc(buf3) · strncpy(buf2) ; ℱ(free(buf1)) ∧ ⊥ ∧ ℱ(free(buf3))) ⇐ X }
FC Violation Found: subtracting “strncpy(buf2)” from “ℱ(!_ (buf2))” leads to false!
```

- ❖ Linear trace processing
- ❖ Embed FCs into program states
- ❖ Trace conjunction + subtraction

The existing solution

```
void *malloc (size_t size);  
// pre: size>0 ∧ _*  
// post: (ret=null ∧ ε) ∨ (ret≠null ∧ malloc(ret))  
// future: ret≠null →  $\mathcal{F}$  (free(ret))
```

$$\frac{f(\bar{x}) [\Phi_{pre}, \Phi_{post}, \Phi_{future}] \in \mathcal{E} \quad [\text{FV-Call}] \quad \Phi <: \Phi_{pre} \quad \{\Phi \circ \Phi_{post}\} e \{\Phi_e\} \quad \Phi_e <: \Phi_{future}}{\{\Phi\} f(\bar{x}); e \{\Phi_{post} \circ \Phi_e\}}$$

Three main limitations:

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Predicates for Bags of Traces and Future Conditions

A false negative example from ProveNFix

```
1 void* mallocN(int n, void **arr,){
2     int i = 0;
3     while (i < n) {
4         arr[i] = malloc(4); i = i+1;}
5     return *arr;}
6
7 void main () {
8     void *arr[5]; mallocN (5, arr);
9     free(arr[0]);/* memory leak */}
```


Predicates for Bags of Traces and Future Conditions

```

1 void* mallocN(int n, void **arr,){
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5   return *arr;}
6
7 void main () {
8   void *arr[5]; mallocN (5, arr);
9   free(arr[0]);/* memory leak */}

```



$mallocN(n, arr) \equiv \text{req: } length(arr) \geq n$

$\text{ens: } (\exists i. \text{true} ; \text{pred}_t([0..n), i) ; \text{pred}_f([0..n), i))$

$\text{pred}_t(B, i) \equiv \Lambda_i^B (arr[i] \neq \text{null} \wedge \text{malloc}(arr[i])) \vee (arr[i] = \text{null} \wedge \epsilon)$

$\text{pred}_f(B, i) \equiv \Lambda_i^B (arr[i] \neq \text{null} \wedge \mathcal{F}(\text{free}(arr[i])))$

When reasoning about main():

8. `void *arr[5]; mallocN (5, arr);`
 $\{(\exists arr, i. length(arr) = 5 ; \text{pred}_t([0..5), i) ; \text{pred}_f([0..5), i))\}$

9. `free(arr[0]);`
 $\{(\exists arr, i. length(arr) = 5 ; \text{pred}_t([0..5), i) \cdot \text{free}(arr[0]) ; \text{pred}_f([1..5), i) \wedge \mathcal{G}(!_ (arr[0])))\}$

FC Violation Found: empty trace “ ϵ ” does not satisfy the obligation “ $\text{pred}_f([1..5), arr)$ ”!

(Specification) $[\text{req: } \pi \text{ ens: } \Delta]$

(Post Summary) $\Delta ::= \bigvee (\pi ; \theta ; F)$

Predicates for Bags of Traces and Future Conditions

```

1 void* mallocN(int n, void **arr,){
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4     arr[i] = malloc(4); i = i+1;}
5   return *arr;}
6
7 void main () {
8   void *arr[5]; mallocN (5, arr);
9   free(arr[0]);/* memory leak */}

```

When reasoning about mallocN():

$$\frac{[\text{FV-While}] \quad \{(\pi \wedge \pi_g; \theta; F)\} e \{(\pi; \theta; F)\}}{\{(\pi; \theta; F)\} \text{ while } \pi_g \text{ do } e \{(\pi \wedge \neg \pi_g; \theta; F)\}}$$



$\text{mallocN}(n, \text{arr}) \equiv \text{req: } \text{length}(\text{arr}) \geq n$

$\text{ens: } (\exists i. \text{true}; \text{pred}_t([0..n], i); \text{pred}_f([0..n], i))$

$\text{pred}_t(B, i) \equiv \Lambda_i^B (\text{arr}[i] \neq \text{null} \wedge \text{malloc}(\text{arr}[i])) \vee (\text{arr}[i] = \text{null} \wedge \epsilon)$

$\text{pred}_f(B, i) \equiv \Lambda_i^B (\text{arr}[i] \neq \text{null} \wedge \mathcal{F}(\text{free}(\text{arr}[i])))$

```

3. while (i < n){
  {(\exists i. \text{true}; \text{pred}_t([0..i], i); \text{pred}_f([0..i], i))}
  4.   arr[i] = malloc(4);
  {(\exists i. \text{true}; \text{pred}_t([0..i+1], i); \text{pred}_f([0..i+1], i))}
  5.   i = i+1;
  {(\exists i. \text{true}; \text{pred}_t([0..i+1], i+1); \text{pred}_f([0..i+1], i+1))}
  6. } {(\exists i. i = n; \text{pred}_t([0..i], i); \text{pred}_f([0..i], i))} \rightsquigarrow
  {(\exists i. \text{true}; \text{pred}_t([0..n], i); \text{pred}_f([0..n], i))}

```


The existing solution

<pre>void *malloc (size_t size); // pre: size>0 ∧ _[★] // post: (ret=null ∧ ε) ∨ (ret≠null ∧ malloc(ret)) // future: ret≠null → \mathcal{F} (free(ret))</pre>	$\frac{f(\bar{x}) [\Phi_{pre}, \Phi_{post}, \Phi_{future}] \in \mathcal{E} \quad [\text{FV-Call}] \quad \Phi <: \Phi_{pre} \quad \{\Phi \circ \Phi_{post}\} e \{\Phi_e\} \quad \Phi_e <: \Phi_{future}}{\{\Phi\} f(\bar{x}); e \{\Phi_{post} \circ \Phi_e\}}$
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Soundness Formalization

- An instrumented semantics for the target language: $[s, \rho, F, e] \xrightarrow{\text{stack, execution trace}} [s', \rho', F', v]$
- Semantic model of trace specifications: $s, \rho \models \pi \wedge \theta$
- A set of forward verification rules: $\{(P; \theta_1; F_1)\} e \{(Q; \theta_2; F_2)\}$

```
Theorem soundness : forall P e Q t1 t2 rho1 rho2 s1 v s2 f1 f2 f3,  
  forward P t1 f1 e Q t2 f2 ->  
  P s1 ->  
  trace_model rho1 t1 ->  
  bigstep s1 rho1 f1 e s2 rho2 f3 v ->  
  Q v s2 /\ trace_model rho2 t2 /\ futureCondEntail f2 f3.
```

It only sound to strengthen the future conditions, so that we do not miss any violations.

The existing solution

<pre>void *malloc (size_t size); // pre: size>0 ∧ _[★] // post: (ret=null ∧ ε) ∨ (ret≠null ∧ malloc(ret)) // future: ret≠null → \mathcal{F} (free(ret))</pre>	$\frac{f(\bar{x}) [\Phi_{pre}, \Phi_{post}, \Phi_{future}] \in \mathcal{E} \quad [\text{FV-Call}] \quad \Phi <: \Phi_{pre} \quad \{\Phi \circ \Phi_{post}\} e \{\Phi_e\} \quad \Phi_e <: \Phi_{future}}{\{\Phi\} f(\bar{x}); e \{\Phi_{post} \circ \Phi_e\}}$
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Coq formalization

Experimental Results

Category	Example APIs	Future Conditions
1. File Ops	fopen, open fclose, close	Finally to close the file descriptor Globally do not access the file descriptor Read-only files cannot be written to
2. Threads	pthread_create pthread_mutex_lock	Finally to pthread_join or detach the thread Finally to pthread_mutex_unlock
3. Memory	free malloc realloc	Globally do not access the pointer Finally free the new pointer Globally the old pointer is not accessed & finally free the new pointer
4. Sockets	socket	Finally to close the socket
5. Database	sqlite3_open	Finally to sqlite3_close the connection
6. URV/NPD	fgets, gethostbyaddr	Check the return value immediately after calls

Write these future conditions manually

Experimental Results

Category	LoC	PrimS	InferredS	InferredInv	Report/Exp.	Time(s)
1	656	8	29	7	14/12	10.05
2	330	4	25	1	4/4	1.97
3	424	6	30	11	25/23	8.87
4	103	2	6	1	3/3	1.76
5	108	4	6	0	4/4	1.97
6	67	10	5	0	5/5	0.56
Total	1,688	34	101	20	55/51	25.18

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False positive due to the limited expressiveness:

```

1 void false_positive1() {
2     int** ptr1= malloc(4);
3     int*  ptr2= malloc(4);
4     *ptr1 = ptr2;
5     free(*ptr1);
6     free(ptr1); }
7 False positive: Memory Leak!

```


Future Conditions

*Thanks for
listening!*

Bug Finding and Repair

- ✓ A novel *future-condition*
- ✓ Compositional temporal analysis
- ✓ Light-weight specification inference
- ✓ Fast and most-automated
- ✓ Proof guided repair
- ✓ Large-scale usability

Verification

- ✓ Handle loops via recursive predicates
- ✓ Efficient (linear) entailment checking
- ✓ Sound weakening when path explosion
- ✓ No false negatives

- ☐ No machine checkable certification
- ☐ Limited expressiveness